APS 2100
Bern HB – Berlin Hbf – Stuttgart Hbf
Future

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Digitale Schiene Deutschland

Advanced Protection System

APS; APS in RCA architecture

**Abstractions** 

Block centric/train centric

Hybrid operation

Built-in migration







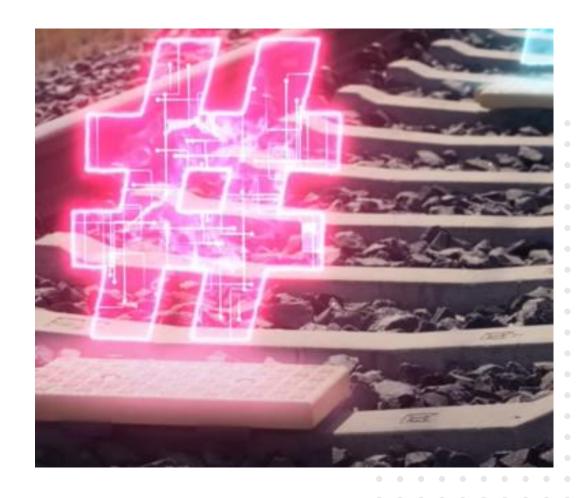


BLÖCKE WAREN GESTERN – ÜBER DIE CHANCEN EINER ZUGENTRISCHEN LST

### **Advanced Protection System (APS)**

FRANK SKOWRON, DB NETZ AG

DMG-SEMINAR – STUTTGART, 28.09.2023



# DigitaleSchieneDeutschland

#### **Digitale Schiene**###### Deutschland

## Government and society expectations require profound technological innovations of the railway system

#### Expectations on the railway system

Modal shift to railway is key to **reduce CO<sub>2</sub>** emissions in traffic sector

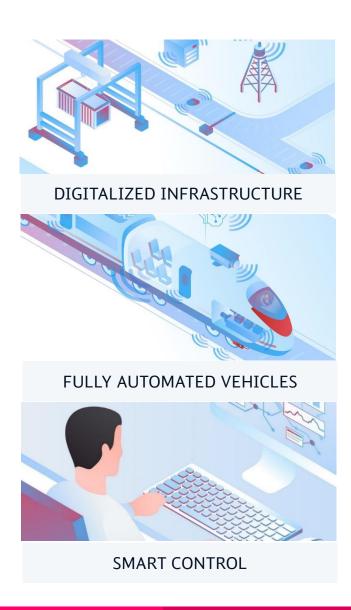
Amount of **rail passengers** expected to **double** by 2030

Share of **freight transport** by rail will **increase** up to 25 %

- We need to to increase rail capacity by up to 35%
- Along with the physical expansion,
   technological innovation and
   digitalisation are the game changers to increase capacity
- Making this lever available to the rail system is the mission of Digitale
   Schiene Deutschland

## Key innovations are being implemented in all main areas of the rail system and create new opportunities





#### **Target picture for the entire rail system**

Trains run **automatically** 

Trains driving at optimal headway

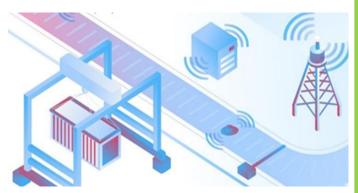
Intelligent **Traffic management** plans and dispatches trains and routes

Interruptions are automatically detected and managed



# DSD starts with the base digitalization of the infrastructure and continues with technological advancements

DBS Target Picture





ETCS L2 & Digital Interlockings (DSTW)

+ additional features/improvements



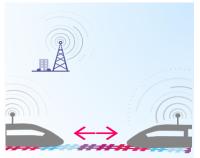
#### HIGHLY AUTOMATED DRIVING

- Trains run highly automated (GoA2)
- Important interim development and migration step
- Enabler for other PBs



#### FULLY AUTOMATED DRIVING

- Trains run fully automated (GoA4)
- Trains monitor their environment
- Trains react on incidents automatically



#### ADVANCED DIGITAL INFRASTRUCTURE

- Novel safety architecture
- Allows driving in optimal headway
- Allows lean infrastructure rollout



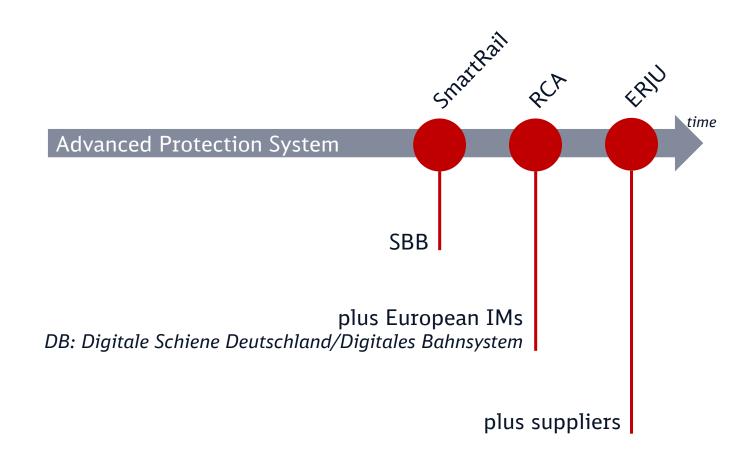
### INTELLIGENT PLANNING AND DISPATCHING

- Automated real-time traffic planning and dispatching
- Automated capacity management and scheduling



#### **Initiatives**

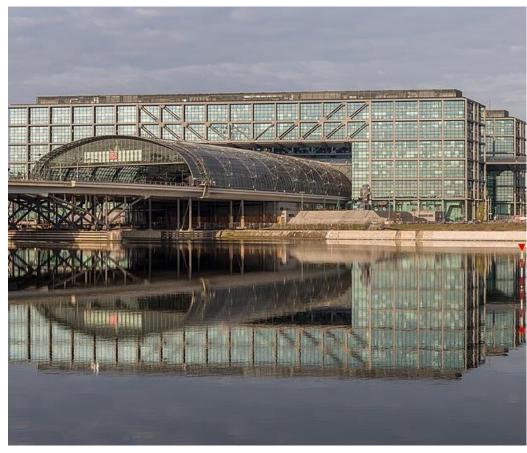






- ❖ System Pillar CCS+
- Innovation Pillar
  - TE Moving Block
  - Demonstrator





Berlin Hbf

Image by Ansgar Koreng – Own creation, CC BY 3.0, https://commons.wikimedia.org/wiki/File:Berlin\_Hauptbahnhof\_Ostseite\_HDR.jpg

### $\rightarrow$ APS

# APS in RCA Architecture

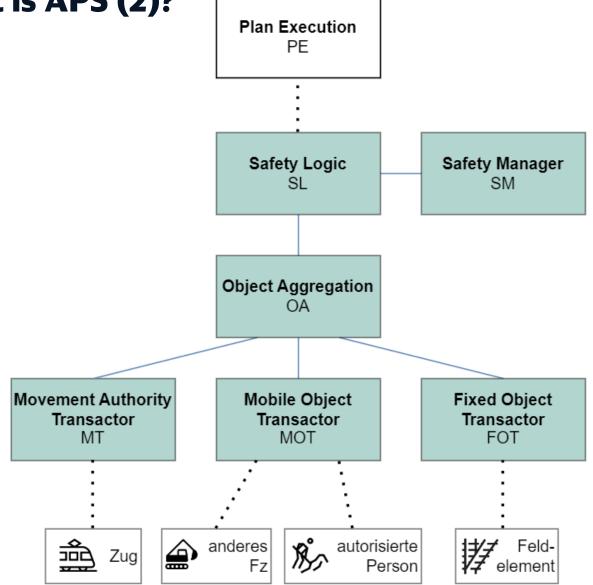
#### What is APS (1)?



- Function **route protection** (today task of interlocking)
- Function trackside **train control** (today task of RBC)
- Train-centric approach (unlike interlocking)







#### **Receives**

- Field Element state change commands
- Movement Permission requests

#### **Grants/Rejects requests**

#### **Controls**

- Trains (ETCS)
- Field Elements (EULYNX SCI)

#### **Reports states of**

- Field elements
- Movable objects
- Movement permissions

#### **RCA Candidate Architecture – APS Scope & Interfaces**



#### Layers

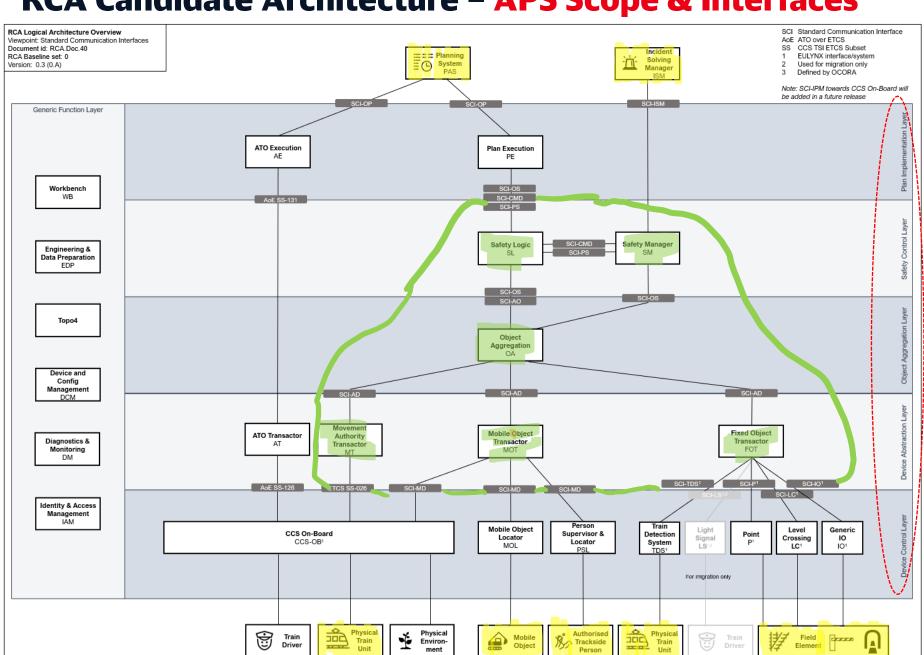
- Plan Implementation
- Safety Control
- Object Aggregation
- Object Abstraction
- Device Control

#### **Benefits**

- Clear responsibilities
- Clear interfaces
- Interchangeability
- Competition, market entry, costs
- Separated life cycles

#### Challenge

Integration

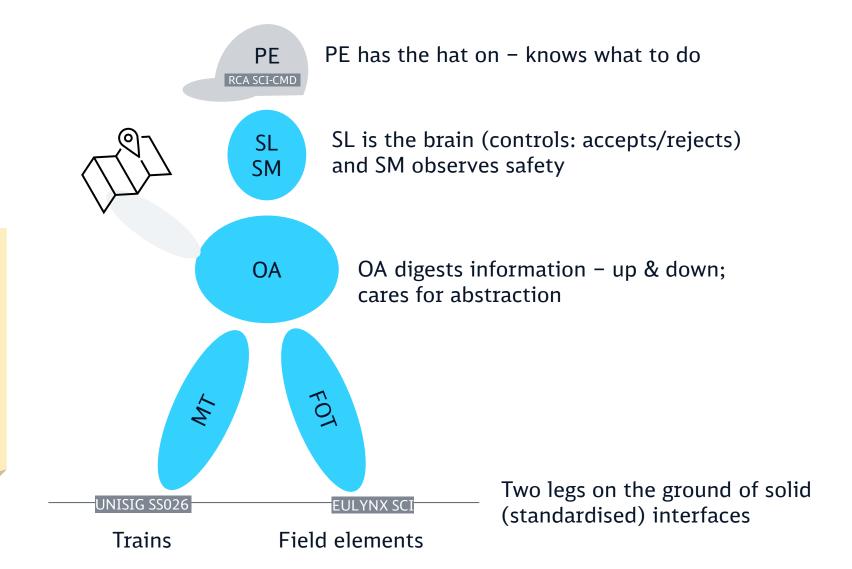


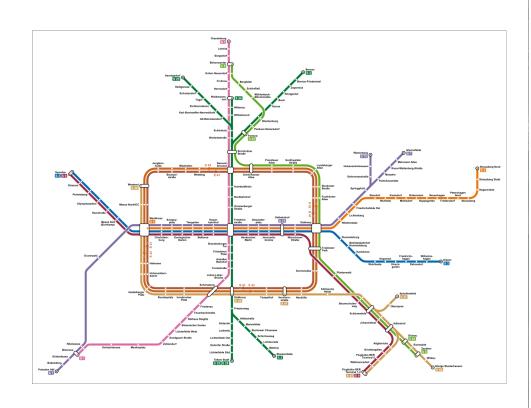
#### **RCA Candidate Architecture - The APS stickman (informal)**



Not shown: the "third leg" to the non-trackbound movable objects

(trackworkers, maintenance vehicles)

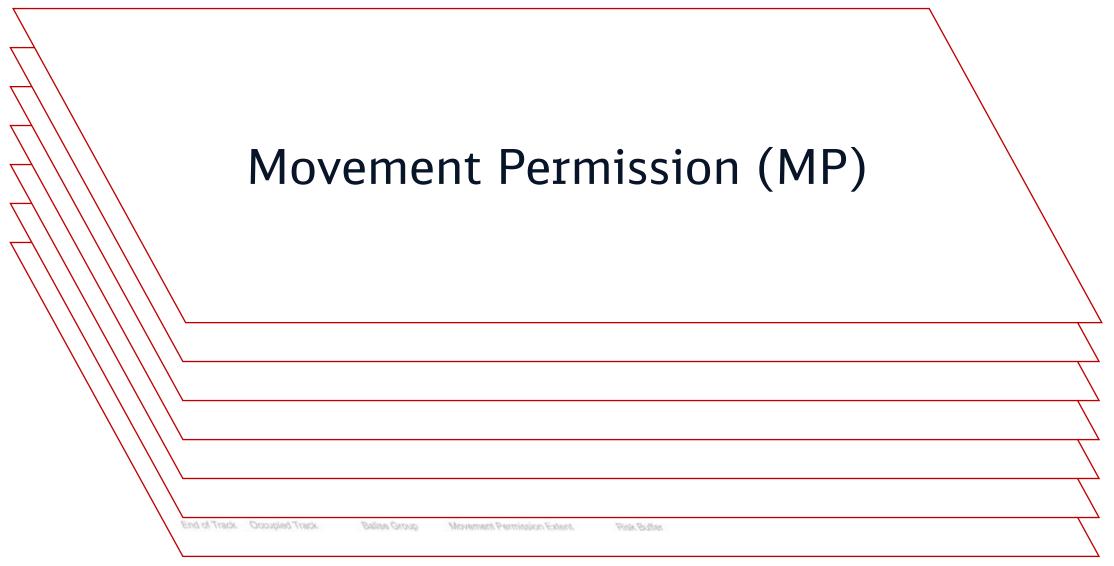






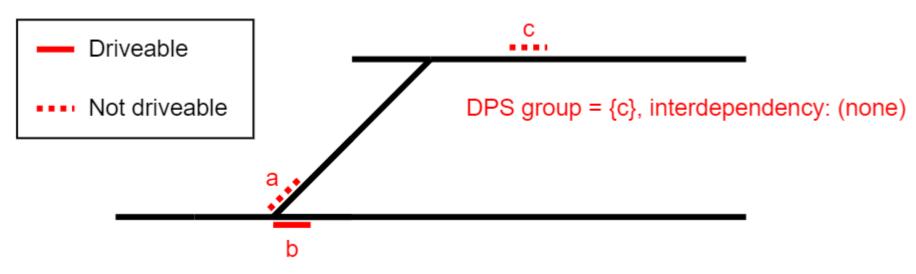
#### **Abstractions**





#### **Abstraction - Driveability (Drive Protection Section DPS)**

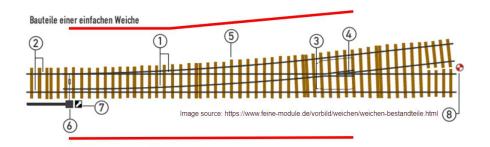




DPS group = {a, b}, interdependency: a xor b

#### **Examples for DPS**

- Point (simple, slip point)
- Derailer
- Level crossing
- Gate
- Movable bridge
- Traverser, turntable

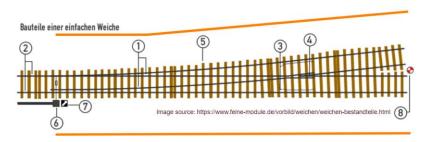


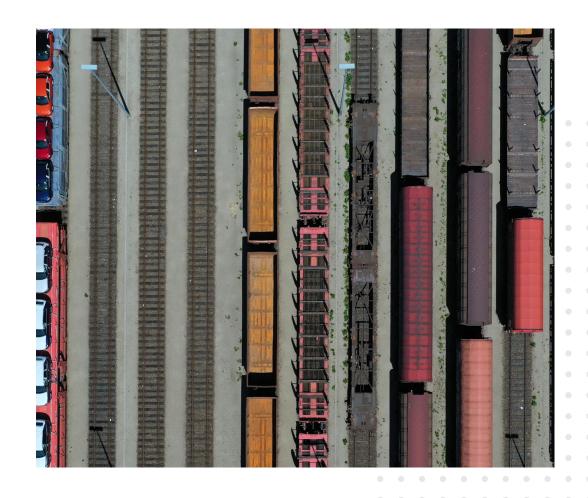
#### **Abstraction: Gauge clearance (Allocation Section AS)**





AS group = {a, b}, interdependency: a xor b





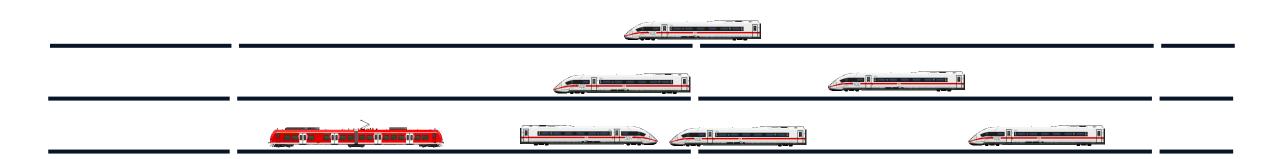


#### Block-centric view: Only auxiliary class of objects in focus



When the interlocking sees this (example: 4 axle counter sections on a straight track)...

... it can be any of these exemplary situations in reality



which means the interlocking view is not oriented to the business object (train) but to **auxiliary objects** (blocks/occupations) which suppresses essential information

#### **Block-centric view: Supplement by train information (RBC)**



With the RBC which knows the business object, both views can be combined



but still the basic functional separation route protection and train control is in place, consider this example

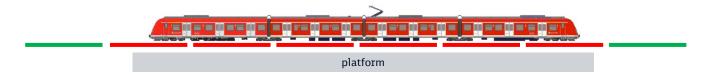


where, when the interlocking can't report a qualified signal stop to the RBC, the RBC cannot *directly* conclude whether the signal was closed triggered by the passing train itself (regular situation) or a preceding train (hazard).

→ The block-centric view is supplemented by train information but **basic (interlocking) principles still hold** and require complicated technical solutions.

#### From block-centric view to train-centric view: Real business object Digitale Schiene Plante Chiene Company Com

Due to capacity improvement needs, in block-centric approach blocks can be (real or virtually) sub-divided so that a train occupies more than one block section



and if this happens in the terminal station and the train has to turn, the interlocking gets a sequence error (expected release order not fulfilled). → Again the mitigation means complicated technical solutions

In **train-centric** view, all this is already built-in.

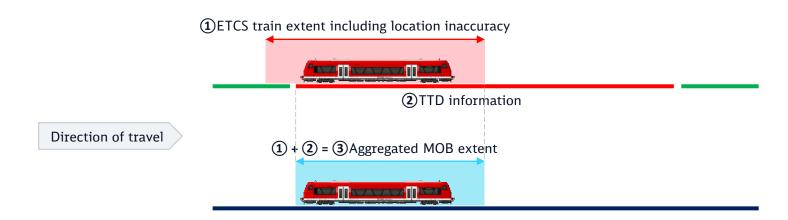


→ None of the two examples will cause a change in APS

#### **Still trackside train-detection equipment (TTD)?**



- From the beginning, APS will support TTD
- This is needed anyway for migration scenarios
- But: the role of TTD will change: from the central **signalling** asset to a pure **location** asset
- This will be used for **object aggregation**



→ Different source of localisation information is aggregated



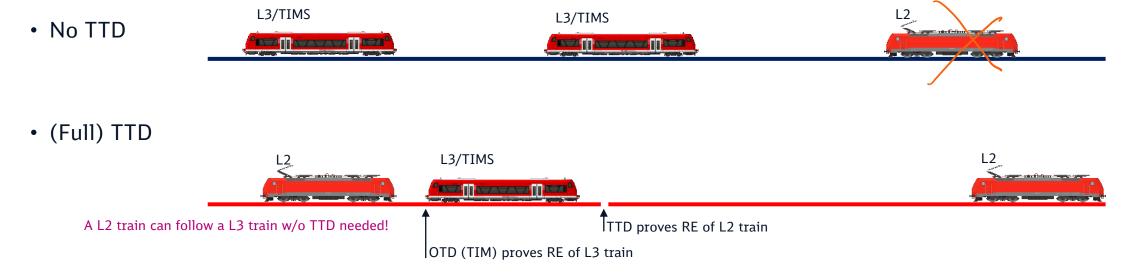
Hybrid shunting loco RhB Geaf 2/2

Image by Kecko – Own creation, CC BY 2.0, https://www.flickr.com/photos/kecko/50259058731/in/photostream/ Hybrid operation

#### **Hybrid/mixed operation (migration)**



- Train front end (FE) is reported by ETCS train position report in both ETCS L2 and L3
- In ETCS L3, the train rear end (RE) can be deduced from integrity + train length
- For a train to follow safely and closely it is important to clear the RE of the preceding train



→APS supports mixed L2/L3 operation from the beginning

(This will be needed to cope with different TIM equipment grades during migration, expected to be a long period.)

#### **APS** inner train-centric safety logic serves <u>all</u> system types

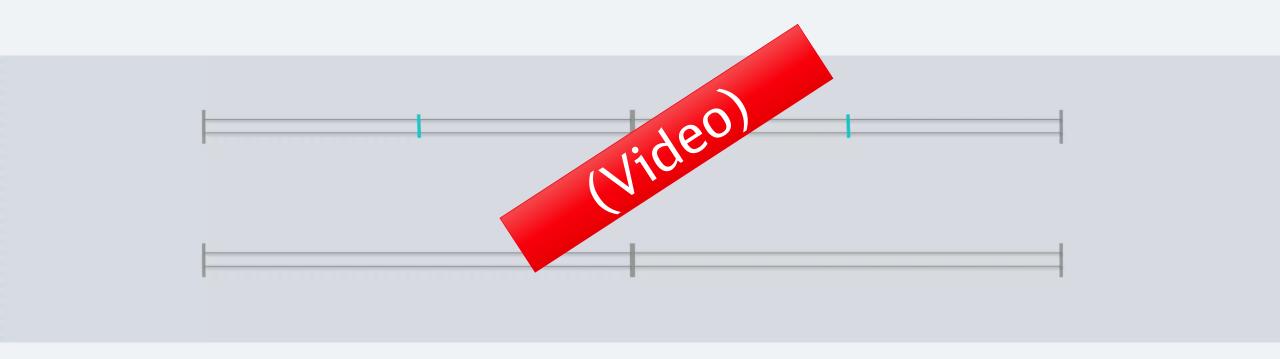
**Digitale Schiene**####### Deutschland

	Fixed block	Hybrid virtual fixed block	Hybrid moving block	Full moving block					
	wasted capacity no TIM	no TIM TIM  W (virtual)	no TIM TIM	TIM TIM TIM					
Rear end located by	TTD	TTD,	OTD	OTD					
Operation	fixed	block	moving block, partially fixed rear end	moving block					
TMS view	block-o	centric	train-centric						
MA target	fixed lo	ocation	any location						
Same train- centric APS	TMS (PE)  MP Request to fixed (virtual) block limits  Flexible MP Request  APS								
No blocks! TTD only for localisation support!		TD: position information	OTD: Position and inte	grity information					

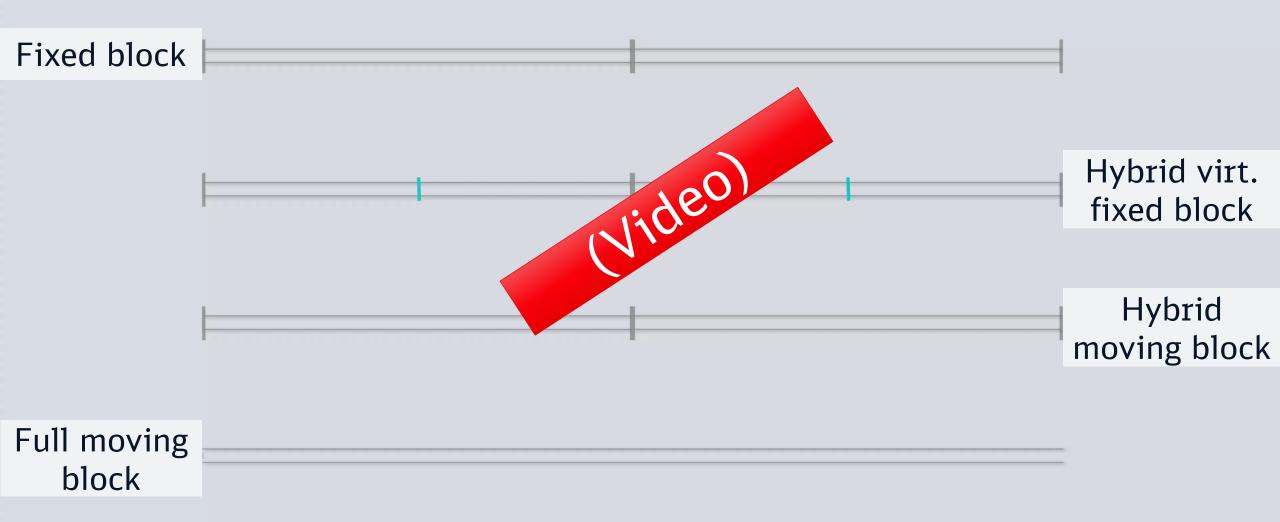
# Fixed Block

# Full moving block

# Hybrid virtual fixed block



# Hybrid moving block



#### **Comparison of signalling principles (video)**



	Train s/h	Compared to							
Fixed block	18	<b>A</b>	<b>†</b> †						
Hybrid virtual fixed block	21		+17%	<b>†</b>					
Hybrid moving block	27		+50%	+29%					
Full moving block	61	1	+238%						

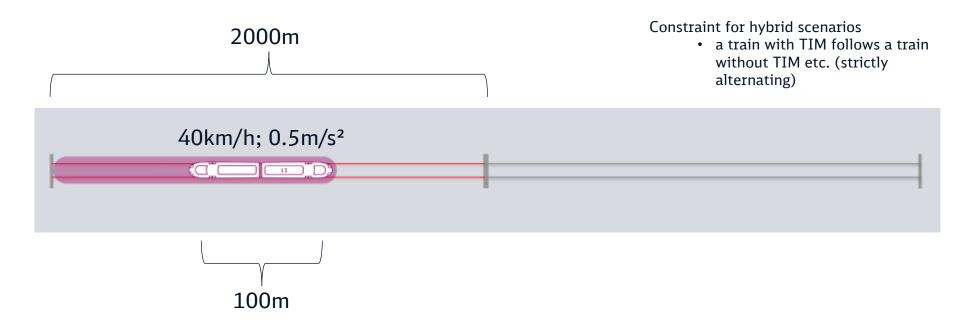




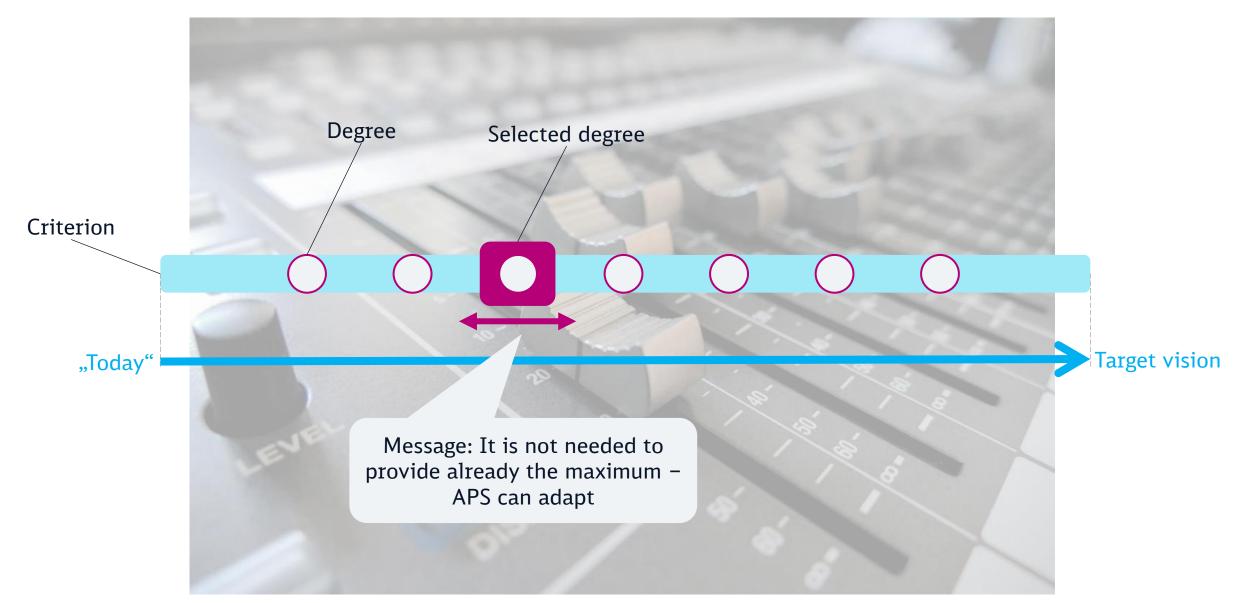
Image by Hans-Jörg Aleff

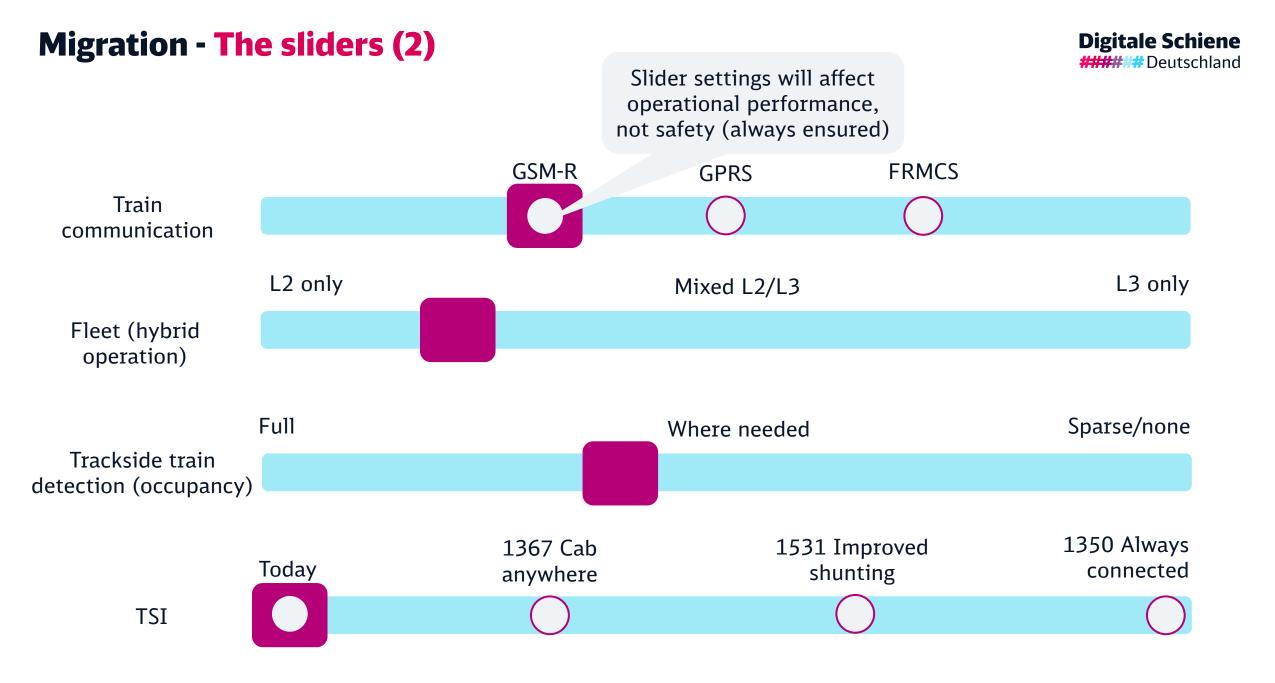
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## → A step too big?

**Built-in migration!** 

#### **Migration - The sliders (1)**





#### Examples. APS will serve them all – environment-driven



Sliders are influenced by external factors (e.g. infrastructure or fleet) and APS can dynamically adapt – no APS sw adaptation needed!

Message: **Don't fear** the target vision's **ambitions** (e.g. *always connected*) – APS will cope with every step within and until.

19 a Elektrische Lokalbahn Payerbach   Windbrücke Raxbahn	19b, 19c, 19d, 19e  19 b Mürzzuschlag-Neuberg Ale Zoge nur 3. 1 3.66								
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Wr Neustact ab 14,38	8.20 14.20 18.50 0.0 at Kapfenberg Hbf. at 7.1711.47)17.17)19. 8.25 14.74 18.55 0.5 w Kapfenberg Landsubhf A 7.091.44)17.14)19. 8.33 14.32 19.00 2.8 Winkt H		•		_	_			•
(Fortsetzung) 15 17 19 21 23 25	8 37  16 36  10 06    3.9   Elnod b Replenberg H   1   10.00 11.03/17.03/17								
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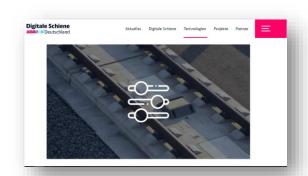
#### Image by Josef Moser

https://commons.wikimedia.org/wiki/File:Fahrpl%C3%A4ne\_H%C3%B6llentalbahn\_Neuberg\_Th%C3 %B6rlerbahn\_Breitenauerbahn\_%C3%9Cbelbach\_1946-47.jpg CC license

#### **Further reading**

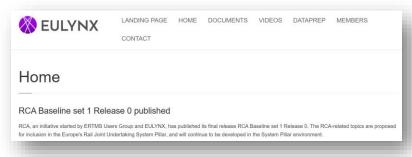


https://digitale-schiene-deutschland.de/Advanced-Protection-System



RCA Baseline 1.0 <a href="https://public.3.basecamp.com/p/KeehzqFmXv5R2N7tGDjaEokq">https://public.3.basecamp.com/p/KeehzqFmXv5R2N7tGDjaEokq</a>

• APS-Documents RCA.Doc.##: 51, 52, 61, 62, 63, 67, 68, 79





Der Eisenbahningenieur 11/2022: Blöcke waren gestern - Chancen einer zugzentrischen LST

# Digitale Schiene ##### Deutschland

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